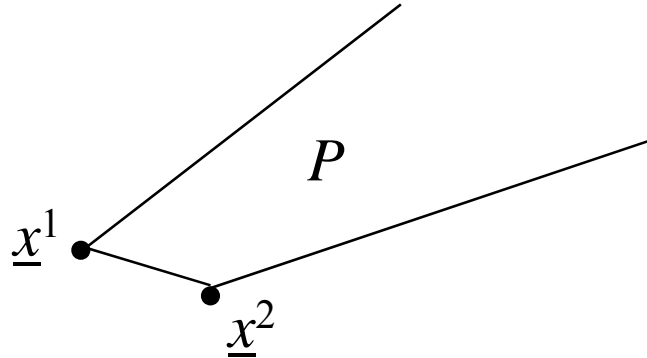


4.3 Basic feasible solutions and vertices of polyhedra

Due to the fundamental theorem of Linear Programming, to solve any LP it ‘suffices’ to consider the vertices (finitely many) of the polyhedron P of the feasible solutions.

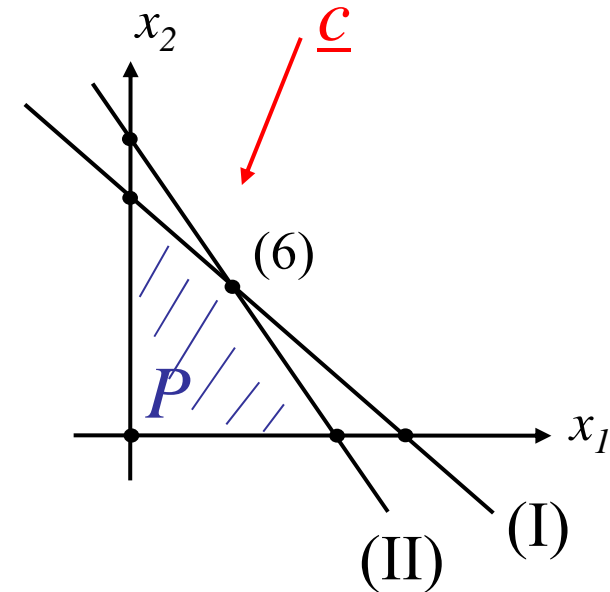


Since the geometrical definition of vertex cannot be exploited algorithmically, we need an algebraic characterization.

Which are the vertices of $P = \{ \underline{x} \in \mathbb{R}^n : A\underline{x} \leq \underline{b}, \underline{x} \geq 0 \}$ with only inequalities?

Example:

$$\begin{aligned} \min & -x_1 - 3x_2 \\ \text{s.t.} & x_1 + x_2 \leq 6 \quad \text{(I)} \\ & 2x_1 + x_2 \leq 8 \quad \text{(II)} \\ & x_1, x_2 \geq 0 \end{aligned}$$



Vertex corresponds to the intersection of the hyperplanes associated to n inequalities.

Example: $n=2$

Vertex (6) is the intersection of hyperplanes of (I) and (II), i.e., solution of equations $x_1 + x_2 = 6$ and $2x_1 + x_2 = 8$.

What about the vertices of polyhedra expressed in standard form?

$$P = \{\underline{x} \in \mathbb{R}^n : A\underline{x} = \underline{b}, \underline{x} \geq 0\}$$

We want to solve LPs in standard form

Easier to describe if we start from a polyhedron

$$P = \{\underline{x} \in \mathbb{R}^n : A\underline{x} \leq \underline{b}, \underline{x} \geq 0\},$$

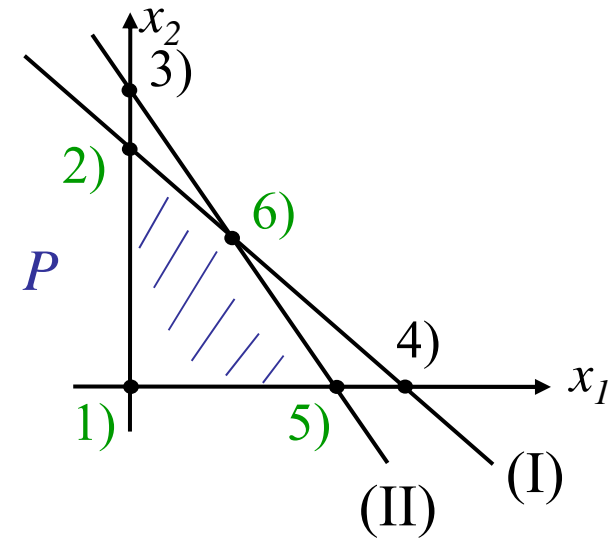
transform it into standard form

$$P' = \{\underline{x} \in \mathbb{R}^n : A\underline{x} + \underline{s} = \underline{b}, \underline{x}, \underline{s} \geq 0\}$$

and rename: $A := [A \mid I]$, $\underline{x} := [\underline{x} \mid \underline{s}]$.

Example:

$$\begin{array}{l} (P) \quad x_1 + x_2 \leq 6 \quad (I) \\ \quad \quad 2x_1 + x_2 \leq 8 \quad (II) \\ \quad \quad x_1, x_2 \geq 0 \end{array} \quad \Longrightarrow \quad \begin{array}{l} (P') \quad x_1 + x_2 + s_1 = 6 \\ \quad \quad 2x_1 + x_2 + s_2 = 8 \\ \quad \quad x_1, x_2, s_1, s_2 \geq 0 \end{array}$$



Taking the intersection of the lines associated to (I) and (II) in P , amounts in P' to let $s_1 = s_2 = 0$.

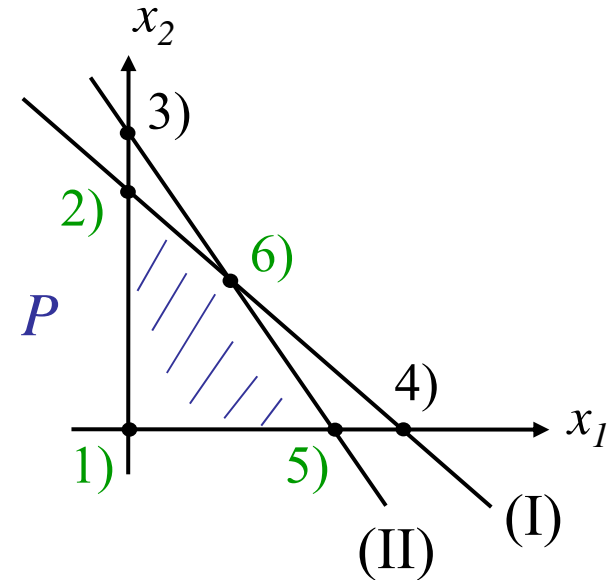
Observation: Every constraint in P corresponds to a slack variable in P' , when the slack variable is set to 0 the constraint is satisfied with $=$.

Example: $s_1 \leftrightarrow x_1 + x_2 \leq 6$, $x_1 \leftrightarrow x_1 \geq 0$

Vertex of P is the intersection of n inequalities in P' it is equivalent to set the corresponding variables in P' to 0.

Example (continued): Compute all the intersections

$$\begin{aligned}x_1 + x_2 + s_1 &= 6 & \text{(I)} \\2x_1 + x_2 + s_2 &= 8 & \text{(II)} \\x_1, x_2, s_1, s_2 &\geq 0\end{aligned}$$



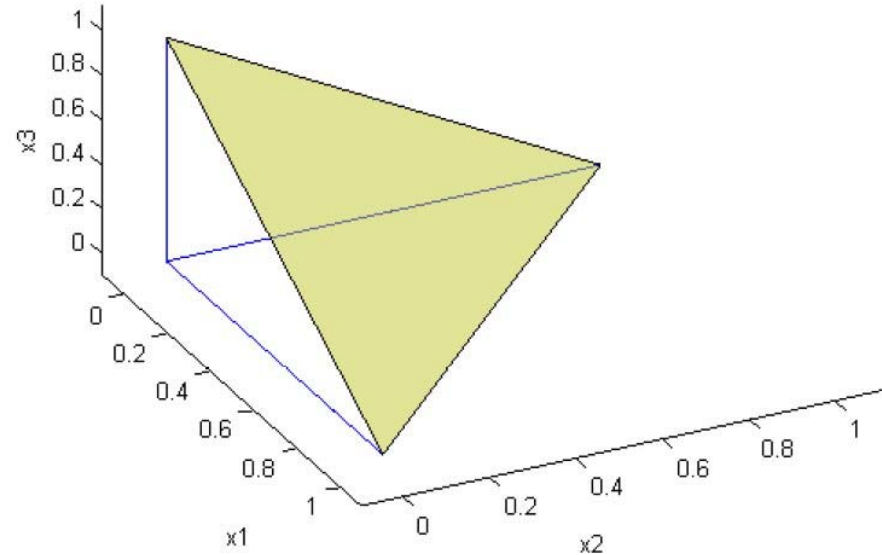
- 1) $x_1 = 0, x_2 = 0 \Rightarrow s_1 = 6, s_2 = 8$
- 2) $x_1 = 0, s_1 = 0 \Rightarrow x_2 = 6, s_2 = 2$
- 3) $x_1 = 0, s_2 = 0 \Rightarrow x_2 = 8, s_1 = -2$
- 4) $x_2 = 0, s_1 = 0 \Rightarrow x_1 = 6, s_2 = -4$
- 5) $x_2 = 0, s_2 = 0 \Rightarrow x_1 = 4, s_1 = 2$
- 6) $s_1 = 0, s_2 = 0 \Rightarrow x_1 = 2, x_2 = 4$

The intersections where some x_j or s_i are < 0 yield infeasible solutions.

Which are the vertices of a polyhedron in standard form?

Example:

$$P = \{ \underline{x} \in \mathbb{R}^3 : x_1 + x_2 + x_3 = 1, \underline{x} \geq 0 \}$$



Property: For any polyhedron $P = \{ \underline{x} \in \mathbb{R}^n : A\underline{x} = \underline{b}, \underline{x} \geq 0 \}$

- the facets (edges in \mathbb{R}^2) are obtained by setting one variable to 0,
- the vertices are obtained by setting $n-m$ variables to 0.

In the example: $3-1=2$ variables set to 0 for vertices.

Algebraic characterization of the vertices

Consider any $P = \{\underline{x} \in \mathbb{R}^n : A\underline{x} = \underline{b}, \underline{x} \geq 0\}$ in standard form.

Assumption: $A \in \mathbb{R}^{m \times n}$ with $m \leq n$ of rank m (A is of full rank)

Equivalent to assume that there are no “redundant” constraints.

Example:
$$\begin{aligned} 2x_1 + x_2 + x_3 &= 2 & \text{(I)} \\ x_1 + x_2 &= 1 & \text{(II)} \\ x_1 + x_3 &= 1 & \text{(III)} \\ x_1, x_2, x_3 &\geq 0 \end{aligned}$$
 Since (I) = (II) + (III),
then (I) can be dropped.

If $m = n$, \exists **unique** solution of $A\underline{x} = \underline{b}$. ($\underline{x} = A^{-1}\underline{b}$)

If $m < n$, $\exists \infty$ solution of $A\underline{x} = \underline{b}$: the system has $n-m$ degrees of freedom ($n-m$ variables can be fixed arbitrarily). If we fix them to 0, we get a vertex.

$$P = \{\underline{x} \in \mathbb{R}^n : A\underline{x} = \underline{b}, \underline{x} \geq 0\}$$

n variables, m constraints, A in $\mathbb{R}^{m \times n}$

Definition: A *basis* of such a matrix A is a subset of m columns of A that are linearly independent and form an $m \times m$ non singular matrix B .

$$A = \left[\underbrace{B}_{m} \mid \underbrace{N}_{n-m} \right]$$

First permute the columns of A , then partition A into $[B|N]$

Let $\underline{x} = \left(\begin{array}{c} \underline{x}_B \\ \text{---} \\ \underline{x}_N \end{array} \right) \left. \begin{array}{l} \} m \text{ components} \\ \} n-m \text{ components} \end{array} \right\}$

Any system $A\underline{x} = \underline{b}$ can be written as

$$B \underline{x}_B + N \underline{x}_N = \underline{b}$$

B is nonsingular

For any set of values for \underline{x}_N , we have

$$\underline{x}_B = B^{-1}\underline{b} - B^{-1}N \underline{x}_N$$

Definitions:

- A *basic solution* is a solution obtained by setting $\underline{x}_N = \underline{0}$ and, consequently, letting $\underline{x}_B = B^{-1}\underline{b}$.
- A basic solution with $\underline{x}_B \geq 0$ is a *basic feasible solution*.
- The variables in \underline{x}_B are the *basic variables* and those in \underline{x}_N are the *non basic variables*.

Note: \underline{x}_B satisfies $A\underline{x} = \underline{b}$ by construction.

Theorem: $\underline{x} \in \mathbb{R}^n$ is a basic feasible solution
if and only if
 \underline{x} is a vertex of $P = \{ \underline{x} \in \mathbb{R}^n : A\underline{x} = \underline{b}, \underline{x} \geq \underline{0} \}$.

Example:

$$\min z = 2x_1 + x_2 + 5x_3$$

$$\text{s.t.} \quad x_1 + x_2 + x_3 + x_4 = 4$$

$$x_1 + x_5 = 2$$

$$x_3 + x_6 = 3$$

$$3x_2 + x_3 + x_7 = 6$$

$$x_i \geq 0 \quad i = 1, \dots, 7$$

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 3 & 1 & 0 & 0 & 0 & 1 \end{pmatrix} \quad \underline{b} = \begin{pmatrix} 4 \\ 2 \\ 3 \\ 6 \end{pmatrix}$$

Choosing columns 4, 5, 6, 7, we have:

$$B = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$B^{-1} = B \Rightarrow \underline{x}_B = B^{-1}\underline{b} = \underline{b} \geq \underline{0}$$

basic feasible solution

Example (continued):

$$\min z = 2x_1 + x_2 + 5x_3$$

$$\text{s.t.} \quad x_1 + x_2 + x_3 + x_4 = 4$$

$$x_1 + x_5 = 2$$

$$x_3 + x_6 = 3$$

$$3x_2 + x_3 + x_7 = 6$$

$$x_i \geq 0 \quad i = 1, \dots, 7$$

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 3 & 1 & 0 & 0 & 0 & 1 \end{pmatrix} \quad \underline{b} = \begin{pmatrix} 4 \\ 2 \\ 3 \\ 6 \end{pmatrix}$$

Choosing columns 2, 5, 6, 7, we have:

$$B = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 3 & 0 & 0 & 1 \end{pmatrix}$$

$$B^{-1} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -3 & 0 & 0 & 1 \end{pmatrix} \Rightarrow \underline{x}_B = \begin{pmatrix} 4 \\ 2 \\ 3 \\ -6 \end{pmatrix} \quad \text{infeasible!}$$

Number of basic feasible solutions

At most one for each choice of $n-m$ variables out of n (nonbasic variables)

$$\# \text{ basic feasible solutions} \leq \binom{n}{n-m} = \frac{n!}{(n-m)!(n-(n-m))!} = \binom{n}{m}$$