

4.7 Sensitivity analysis in Linear Programming

Evaluate the “sensitivity” of an optimal solution with respect to variations in the data (model parameters).

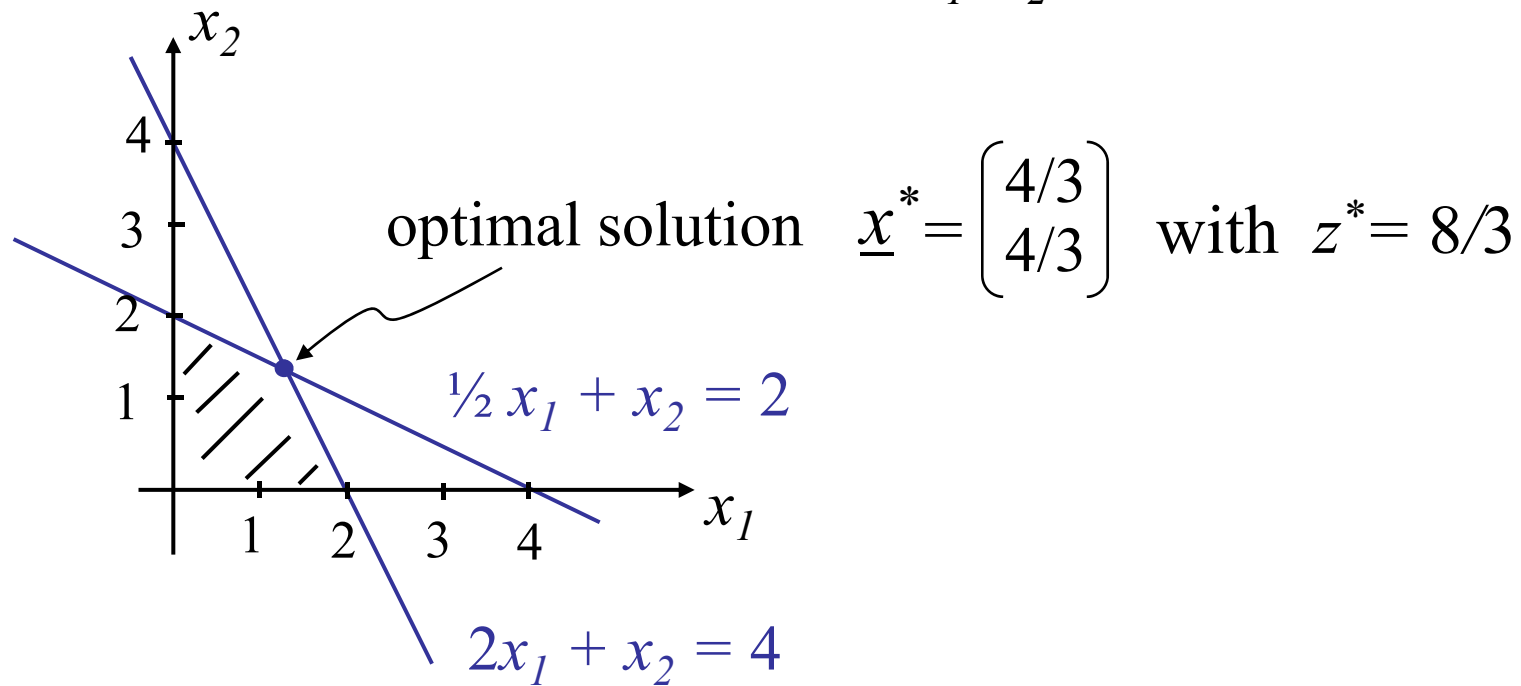
Example: Production planning

$$\begin{aligned} \max \quad & \sum_{j=1}^n p_j x_j && \text{profit} \\ & \sum_{j=1}^n a_{ij} x_j \leq b_i && \text{availability } i\text{-th resource} \quad 1 \leq i \leq m \\ & x_j \geq 0 && 1 \leq j \leq n \end{aligned}$$

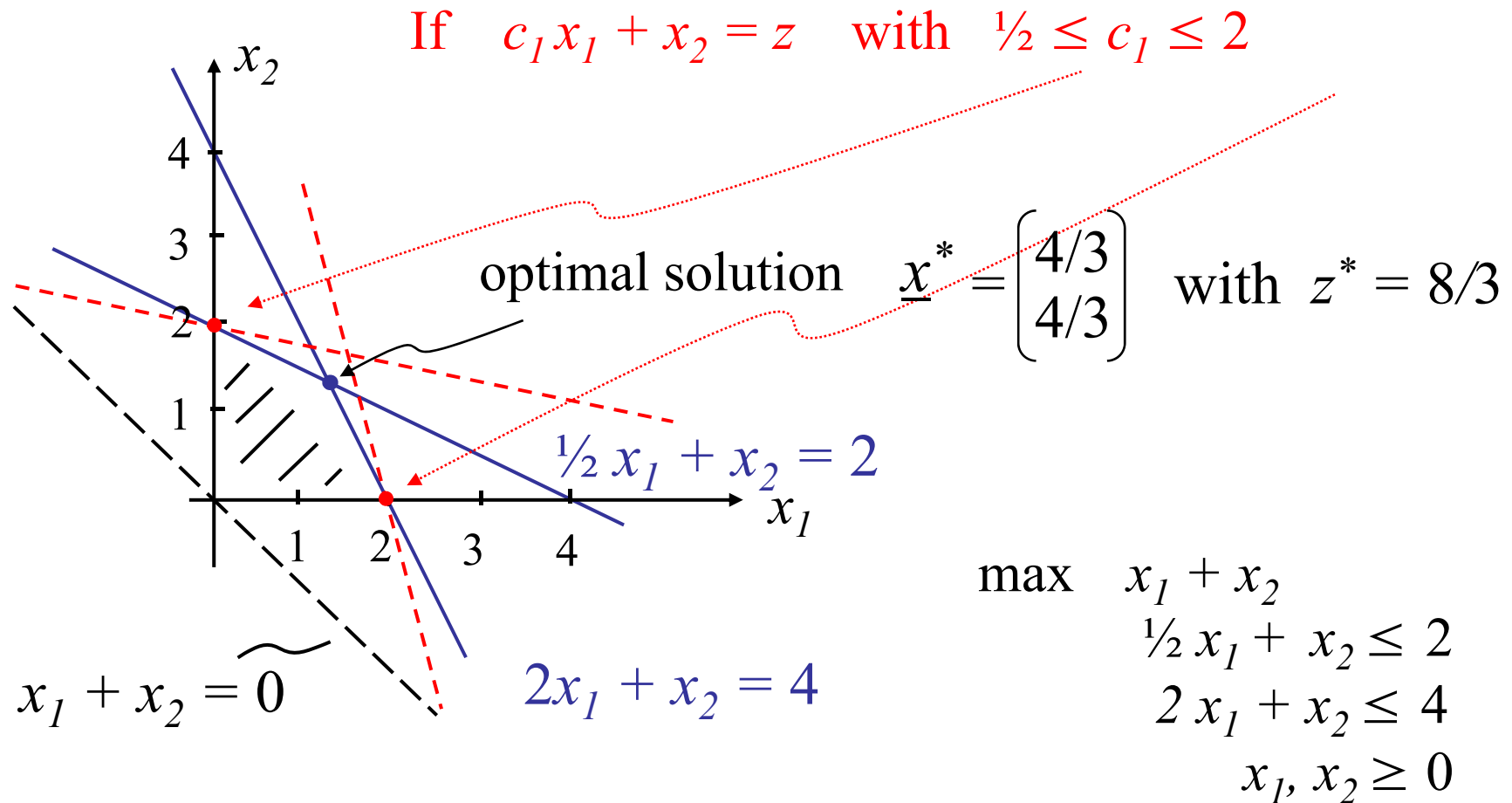
4.7.1 Geometric interpretation

Example:

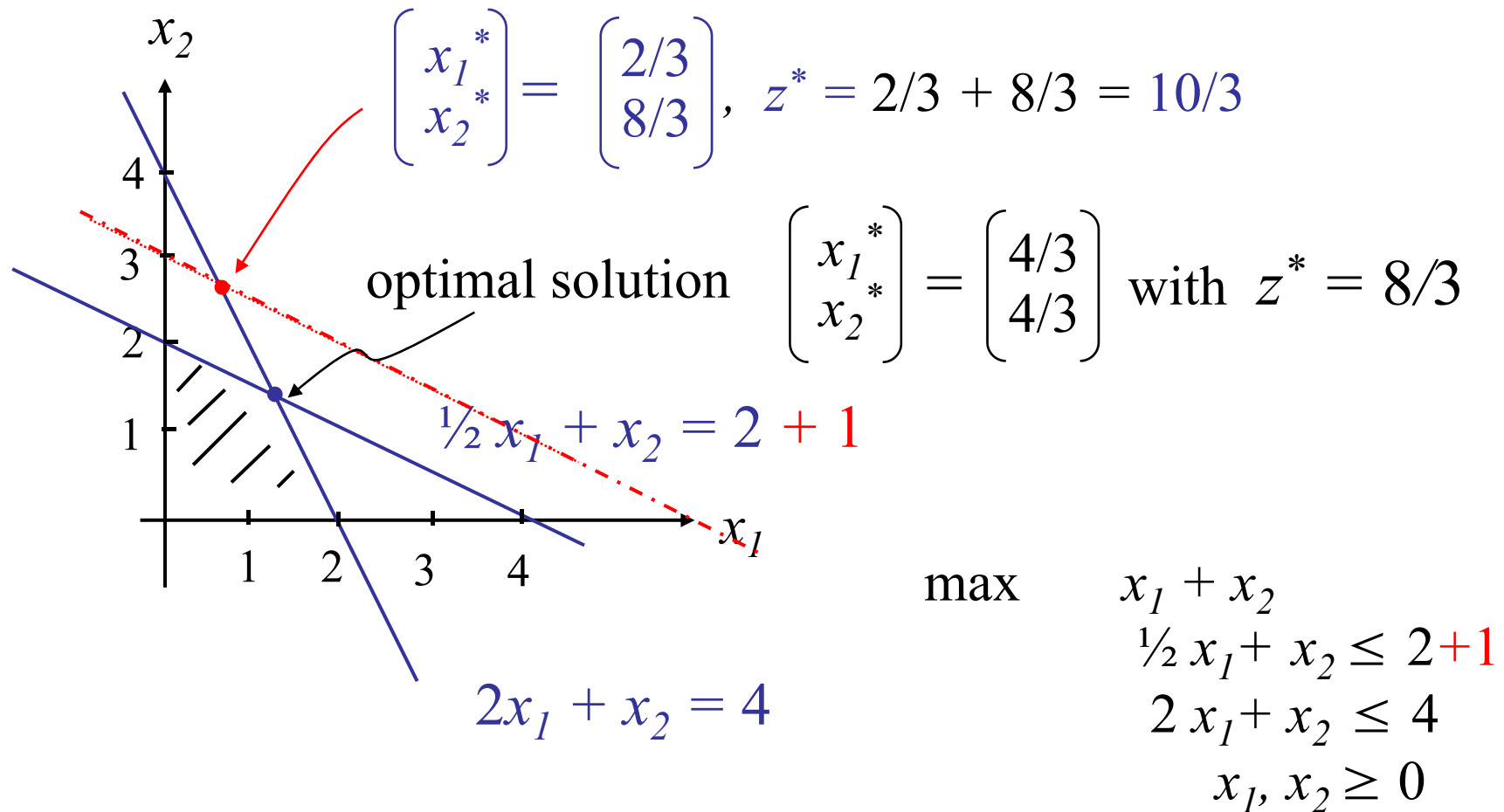
$$\begin{aligned} \max \quad & x_1 + x_2 \\ & \frac{1}{2} x_1 + x_2 \leq 2 \\ & 2x_1 + x_2 \leq 4 \\ & x_1, x_2 \geq 0 \end{aligned}$$



Variation of the objective function coefficients



Variations of the right-hand-side terms



Definition:

The shadow price of the *i*-th resource = maximum price the company is willing to pay to buy an additional unit of *i*-th resource.

Shadow price of the first resource = $10/3 - 8/3 = 2/3$

\parallel
 Z^*

4.7.2 Sensitivity analysis: algebraic form

Evaluate the “sensitivity” of an optimal solution when the model parameters (c_j, a_{ij}, b_i) vary.

Given $\min \underline{c}^T \underline{x}$ and optimal basic solution \underline{x}^*

$$(P) \quad \begin{array}{l} A\underline{x} = \underline{b} \\ \underline{x} \geq \underline{0} \end{array} \quad \begin{array}{l} \underline{x}_B^* = B^{-1}\underline{b} \geq \underline{0} \\ \underline{x}_N^* = \underline{0} \end{array}$$

Within which limits the basis B remains optimal?

Conditions:

$$\begin{array}{ll} 1) B^{-1}\underline{b} \geq \underline{0} & \underline{\text{feasibility}} \\ 2) \bar{\underline{c}}_N^T = \underline{c}_N^T - \underline{c}_B^T B^{-1}N \geq \underline{0}^T & \underline{\text{optimality}} \end{array}$$

Topic of the **4th computer laboratory** session.

Variation of right-hand-side terms

$$\underline{b}' := \underline{b} + \delta_k \underline{e}_k \quad \text{with} \quad \underline{e}_k = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ 0 \\ 0 \end{bmatrix} \leftarrow k \quad 1 \leq k \leq n$$

The basis B with the basic solution

$$\underline{x}^* = \begin{pmatrix} B^{-1}(\underline{b} + \delta_k \underline{e}_k) \\ \underline{0} \end{pmatrix} \quad \bar{c}_N \text{ do not vary}$$

remains optimal as long as

$$B^{-1}(\underline{b} + \delta_k \underline{e}_k) \geq \underline{0} \quad \Rightarrow \quad \underbrace{B^{-1}\underline{b} \geq -\delta_k B^{-1}\underline{e}_k}$$

m inequalities that define an interval of variation for δ_k

The basis B remains optimal, but the optimal basic feasible solution changes.

The objective function values goes from $\underline{c}_B^T B^{-1} \underline{b}$ to $\underline{c}_B^T B^{-1} (\underline{b} + \delta_k \underline{e}_k)$

$$\Rightarrow \Delta z^* = \underbrace{\underline{c}_B^T B^{-1}}_{\underline{y}^{*T}} (\delta_k \underline{e}_k) = \delta_k \underbrace{y_k^*}_{\text{shadow price!}}$$

$\frac{\partial z^*}{\partial b_k}$
 ← optimal value of the dual variable

Variation of the cost coefficients

Given $\underline{c}' := \underline{c} + \delta_k \underline{e}_k$

a basis B remains optimal as long as

$$\bar{\underline{c}}'^T_N := \underline{c}'^T_N - \underline{c}'^T_B B^{-1}N \geq \underline{0}$$

In such a case, the optimal basic (feasible) solution does not change:

$$\begin{cases} \underline{x}^*_B = B^{-1}\underline{b} \\ \underline{x}^*_N = \underline{0} \end{cases}$$

If x_k is a nonbasic variable

$$\bar{\underline{c}}'^T_N = \underline{c}'^T_N - \underline{c}'^T_B B^{-1}N \geq \underline{0}^T \quad \text{con } \underline{c}'^T_B = \underline{c}^T_B$$

$$\begin{aligned} \bar{\underline{c}}'^T_N &= (\underline{c}^T_N + \delta_k \underline{e}^T_k) - \underline{c}^T_B B^{-1}N \\ &= (\underline{c}^T_N - \underline{c}^T_B B^{-1}N) + \delta_k \underline{e}^T_k \\ &= \bar{\underline{c}}^T_N + \delta_k \underline{e}^T_k \geq \underline{0}^T \\ &\Rightarrow \delta_k \geq -\bar{c}_k \end{aligned}$$

Reduced cost = **max decrease of c_k for which B remains optimal** (larger decrease $\Rightarrow \bar{c}'_k < 0$)

$$\Delta z^* = 0 \quad \text{since} \quad z^* = \underline{c}^T_B B^{-1}\underline{b} = \underline{c}^T_B \underline{x}^*_B$$

If x_k is a basic variable

$$\bar{\underline{c}}'^T_N = \underline{c}'^T_N - \underline{c}'^T_B B^{-1}N \geq \underline{0}^T \quad \text{with} \quad \underline{c}'^T_N = \underline{c}^T_N$$

$$\bar{\underline{c}}'^T_N = \underline{c}^T_N - (\underline{c}^T_B + \delta_k \underline{e}^T_k) B^{-1}N$$

$$= (\underline{c}^T_N - \underline{c}^T_B B^{-1}N) - \delta_k \underline{e}^T_k B^{-1}N$$

$$\Rightarrow \bar{\underline{c}}^T_N - \delta_k \underline{\rho}^T_k \geq \underline{0}^T$$

where $\underline{\rho}^T_k$ k -the row of $B^{-1}N$

$$\underbrace{\bar{\underline{c}}^T_N \geq \delta_k \underline{\rho}^T_k}$$

$n-m$ inequalities that define a variation interval for δ_k

In such a case

$$\Delta z^* = \delta_k \underline{e}_k^T \underbrace{B^{-1} \underline{b}}_{\underline{x}_B^*} = \delta_k x_k^* \longleftarrow \frac{\partial z^*}{\partial c_k}$$

Similar analysis for the coefficients a_{ij}

Example: sensitivity analysis

Initial tableau:

min

$$\begin{aligned} \underline{c}^T \underline{x} \\ A\underline{x} &= \underline{b} \\ \underline{x} &\geq \underline{0} \end{aligned}$$

		x_1	x_2	x_3	initial basis x_4 x_5 x_6		
$-z$	0	-3	-1	-3	0	0	0
x_4	2	2	1	1	1	0	0
x_5	5	1	2	3	0	1	0
x_6	6	2	2	1	0	0	1

↑
 b

}
 I

Optimal tableau:

$$\bar{\underline{c}}^T_N := \underline{c}^T_N - \underline{c}^T_B B^{-1}N$$

“pivoting”
operations \equiv
premultiply by B^{-1}

		x_1	x_2	x_3	x_4	x_5	x_6
$-z$	$27/5$	0	$7/5$	0	$6/5$	$3/5$	0
x_1	$1/5$	1	$1/5$	0	$3/5$	$-1/5$	0
x_3	$8/5$	0	$3/5$	1	$-1/5$	$2/5$	0
x_6	4	0	1	0	-1	0	1

\uparrow $B^{-1}\underline{b}$
 \uparrow
 \uparrow
 \uparrow

$B^{-1}N$
 $B^{-1}I = B^{-1}$

Thus

$$\underline{x}_B = \begin{pmatrix} x_1 \\ x_3 \\ x_6 \end{pmatrix} \quad B = \begin{pmatrix} 2 & 1 & 0 \\ 1 & 3 & 0 \\ 2 & 1 & 1 \end{pmatrix} \quad B^{-1} = \begin{pmatrix} \frac{3}{5} & -\frac{1}{5} & 0 \\ -\frac{1}{5} & \frac{2}{5} & 0 \\ -1 & 0 & 1 \end{pmatrix}$$

$$B^{-1}\underline{b} = \begin{pmatrix} \frac{1}{5} \\ \frac{8}{5} \\ 4 \end{pmatrix} \quad \underline{c}_B = \begin{pmatrix} -3 \\ -3 \\ 0 \end{pmatrix} \quad \underline{x}_N = \begin{pmatrix} x_2 \\ x_4 \\ x_5 \end{pmatrix} \quad \underline{c}_N = \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix}$$

Optimal dual solution:

$$\underline{y}^T = \underline{c}_B^T B^{-1} = (-3 \quad -3 \quad 0) \begin{pmatrix} \frac{3}{5} & -\frac{1}{5} & 0 \\ -\frac{1}{5} & \frac{2}{5} & 0 \\ -1 & 0 & 1 \end{pmatrix} = \left(-\frac{6}{5} \quad -\frac{3}{5} \quad 0\right)$$

- Variations of \underline{b} : $\underline{b}' := \underline{b} + \delta_k \underline{e}_k$ $\underline{e}_k = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \leftarrow k$

$$\underline{x}_B^* = \begin{pmatrix} B^{-1}(\underline{b} + \delta_k \underline{e}_k) \\ \underline{0} \end{pmatrix} \text{ remains optimal}$$

as long as $B^{-1}(\underline{b} + \delta_k \underline{e}_k) \geq \underline{0} \Rightarrow B^{-1}\underline{b} \geq -\delta_k B^{-1}\underline{e}_k$
 $k = 1, 2, 3$

$$\underline{k} = 1: \begin{pmatrix} 1/5 \\ 8/5 \\ 4 \end{pmatrix} \geq -\delta_1 \begin{pmatrix} 3/5 \\ -1/5 \\ -1 \end{pmatrix} \Rightarrow \begin{cases} -1/3 \leq \delta_1 \\ 8 \geq \delta_1 \\ 4 \geq \delta_1 \end{cases} \Rightarrow -1/3 \leq \delta_1 \leq 4$$

$$\underline{k} = 2: -4 \leq \delta_2 \leq 1 \quad \underline{k} = 3: -4 \leq \delta_3$$

- Variations of c : $\underline{c}' := \underline{c} + \delta_k \underline{c}_k$

For x_k nonbasic, B remains optimal if and only if $\delta_k \geq -\bar{c}_k$

$$\begin{aligned} \delta_2 &\geq -7/5 \\ \delta_4 &\geq -6/5 \\ \delta_5 &\geq -3/5 \end{aligned} \quad \text{reduced cost}$$

For x_k basic, B remains optimal if and only if

$$\bar{c}_N^T \geq \delta_k \underline{e}_k^T B^{-1} N$$

$$\bar{c}_N = \begin{pmatrix} 7/5 \\ 6/5 \\ 3/5 \end{pmatrix} \quad B^{-1} N = \begin{pmatrix} 3/5 & -1/5 & 0 \\ -1/5 & 2/5 & 0 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 2 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1/5 & 3/5 & -1/5 \\ 3/5 & -1/5 & 2/5 \\ 1 & -1 & 0 \end{pmatrix}$$

$$\underline{k = 1}: \quad \begin{pmatrix} 7/5 & 6/5 & 3/5 \end{pmatrix} \geq \delta_1 \begin{pmatrix} 1/5 & 3/5 & -1/5 \end{pmatrix}$$

$$-3 \leq \delta_1 \leq 2$$

$$\underline{k = 3}: \quad \begin{pmatrix} 7/5 & 6/5 & 3/5 \end{pmatrix} \geq \delta_3 \begin{pmatrix} 3/5 & -1/5 & 2/5 \end{pmatrix}$$

$$-6 \leq \delta_3 \leq 3/2$$

$$\underline{k = 6}: \quad \begin{pmatrix} 7/5 & 6/5 & 3/5 \end{pmatrix} \geq \delta_6 \begin{pmatrix} 1 & -1 & 0 \end{pmatrix}$$

$$-6/5 \leq \delta_6 \leq 7/5$$